

Third Crete Regional Meeting in String Theory

June 23 – July 2 2005
Orthodox Academy of Crete
Kolymbari – Greece

Geometrical fluxes and
Scherk–Schwarz deformations

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1. Introduction

- Superstrings and M-theory compactifications can give 4d vacua with exact or (spontaneously) broken supersymmetries.

- Phenomenologically interesting are those with

$$N = 8, 4 \rightarrow N = 1 \rightarrow N = 0$$

- The underlying $D = 10$ theories encode $N \geq 4$ constrained structure which can be used to obtain useful information on the effective $N = 1$ supergravity.
- The 4d $N = 1$ theories, typically include moduli fields whose vacuum expectation values are undetermined.

Some of these moduli are the: dilaton field Φ , internal metric fields G_{IJ} , and p -form fields F^p

Generating a potential for some of the moduli is essential in order to :

- reduce the number of massless scalars
- induce supersymmetry breaking
- determine the (3+1)d geometry

In the $N \geq 4$ supergravity theories, the only available tool for generating a non-trivial potential is the “gauging”.

“Gauging” \rightarrow We introduce in the theory a gauge group G acting on the vector fields of the gravitational and the vector supermultiplets.

The important fact is: The kinetic terms of the fields in the gauged theory, remain the same as in the ungauged theory.

In the language of $N = 1$ ($\leftarrow N \geq 4$)

The gauging modifications are non-trivial for the the superpotential W .

The Kähler potential K remains the same as in the ungauged theory.

To be more precise consider the case of superstring constructions **with an $N = 4$ supersymmetry:**

- Heterotic on T^6
- Type IIA or IIB on $K3 \times T^2$
- Type IIA, IIB on orientifolds
- Type IIA, IIB asymmetric (4,0)
- ...

2. $N = 4$ Gauging $\leftrightarrow N = 1$ Superpotential

Independently of our starting point, the scalar manifold M of the induced $N = 4$ effective supergravity is identical for all superstring constructions.

$$M = \left(\frac{SU(1, 1)}{U(1)} \right)_S \times \left(\frac{SO(6, 6 + n)}{SO(6) \times SO(6 + n)} \right)_{T_A, U_A, Z_I}$$

After $Z^2 \times Z^2$ orbifold (CY) projections

$N = 4 \rightarrow N = 1$ and $M \rightarrow K$

$$K = \left(\frac{SU(1, 1)}{U(1)} \right)_S \times \left(\frac{SO(2, 2 + n_1)}{SO(2) \times SO(2 + n_1)} \right)_{T_1, U_1, Z_1^I} \\ \times \left(\frac{SO(2, 2 + n_2)}{SO(2) \times SO(2 + n_2)} \right)_{T_2, U_2, Z_2^I} \\ \times \left(\frac{SO(2, 2 + n_3)}{SO(2) \times SO(2 + n_3)} \right)_{T_3, U_3, Z_3^I}$$

$$\begin{aligned}
K &= -\log(S + \bar{S}) \\
&- \log\left((T_1 + \bar{T}_1)(U_1 + \bar{U}_1) - (Z_1 + \bar{Z}_1)^2\right) \\
&- \log\left((T_2 + \bar{T}_2)(U_2 + \bar{U}_2) - (Z_2 + \bar{Z}_2)^2\right) \\
&- \log\left((T_3 + \bar{T}_3)(U_3 + \bar{U}_3) - (Z_3 + \bar{Z}_3)^2\right).
\end{aligned}$$

The above choice of parameterization is a solution to the $N = 4$ constraints after $Z^2 \times Z^2$ orbifold projections $N = 4 \rightarrow N = 1$:

S -manifold

$$\begin{aligned}
|\phi_0|^2 - |\phi_1|^2 &= \frac{1}{2} \quad \longrightarrow \\
\phi_0 - \phi_1 &= \frac{1}{(S + \bar{S})^{1/2}}, & \phi_0 + \phi_1 &= \frac{S}{(S + \bar{S})^{1/2}}
\end{aligned}$$

T_A, U_A, Z_A^I -manifolds

$$|\sigma_A^1|^2 + |\sigma_A^2|^2 - |\rho_A^1|^2 - |\rho_A^2|^2 - |\Phi_A^I|^2 = \frac{1}{2}$$

$$(\sigma_A^1)^2 + (\sigma_A^2)^2 - (\rho_A^1)^2 - (\rho_A^2)^2 - (\Phi_A^I)^2 = 0$$

$$\sigma_A^1 = \frac{1 + T_A U_A - (Z_A^I)^2}{2Y_A^{1/2}}, \quad \sigma_A^2 = i \frac{T_A + U_A}{2Y_A^{1/2}}$$

$$\rho_A^1 = \frac{1 - T_A U_A - (Z_A^I)^2}{2Y_A^{1/2}}, \quad \rho_A^2 = i \frac{T_A - U_A}{2Y_A^{1/2}}$$

$$\Phi_A^I = \frac{i Z_A^I}{2Y_A^{1/2}}, \quad K_A = -\log Y_A$$

The **superpotential of the $N = 1$ supergravity** is determined by the **gravitino mass terms in $N = 4$** after the $Z^2 \times Z^2$ orbifold projections.

Gravitino mass term: $e^{K/2} W =$

$$(\phi_0 - \phi_1) f_{IJK} \Phi_1^I \Phi_2^I \Phi_3^I + (\phi_0 + \phi_1) \bar{f}_{IJK} \Phi_1^I \Phi_2^I \Phi_3^I$$

$$\Phi_A^I = \{ \sigma_A^1, \sigma_A^2; \rho_A^1, \rho_A^2, \Phi_A^I \}$$

Both f_{IJK} \bar{f}_{IJK} are the gauge structure constants of the $N = 4$ “mother” theory.

In the heterotic, the term proportional to f_{IJK} give rise to a perturbative “electric gauging”. The term proportional to \bar{f}_{IJK} provide the non-perturbative “magnetic gauging”.

- What is the origin of f_{IJK} \bar{f}_{IJK} in the superstrings and M -theory?
- What are the deformation parameters of the 2d σ -model in correspondence with the $N = 4$ gauging coefficients f_{IJK} \bar{f}_{IJK} ?

3. Fluxes and $N = 4$ Gauging

In general, the breaking of SUSY requires a gauging with **non-zero f_{IJK}** involving the fields

$\sigma_A^1, \sigma_A^2; \rho_A^1, \rho_A^2 \longrightarrow$ gauging involving the
 $N = 4$ graviphotons
 \longrightarrow gauging of the R-symmetry

In string and M-theory, f_{IJK} and \bar{f}_{IJK} are generated by **non-zero FLUXES:**
Electric and Magnetic fluxes,
RR and fundamental p -form fields:

- **3-form fluxes H^3** , in the NS-sector of heterotic, type IIA and type IIB
- **F^p , p -form fluxes**, in M-theory and in the RR sector of type IIA and type IIB

- F^2 **2-form fluxes**, in heterotic ($E_8 \times E_8$ or $SO(32)$) as well as in type I
- ω^3 **3-form geometrical fluxes**, in all strings and M-theory

Special cases have already been studied:

- H^3 in heterotic
 - Derendinger, Ibanez, Nilles, 85, 86;
 - Dine, Rohm, Seiberg, Witten, 85;
 - Strominger, 86; Rohm, Witten, 86.
- Simultaneous presence of NS, RR H^3 and F^3 in Type IIB.
 - Frey, Polchinski, 02;
 - Giddings, Kachru, Polchinski, 02;
 - Kachru, Schulz, Trivedi, 03;
 - Kachru, Schulz, Tripathy, Trivedi, 03;
 - Derendinger, Kounnas,
 - Petropoulos, Zwirner, 04.

- ω^3, H^3, F^2 , exact string solution via freely acting orbifold.

→

Generalization of the Scherk–Schwarz deformation to superstring theory.

Rohm, 84;
Kounnas, Porrati, 88;
Ferrara, Kounnas,
Porrati, Zwirner, 89;
Kounnas, Rostand, 90;
Kiritsis, Kounnas, 96;
Kiritsis, Kounnas,
Petropoulos, Rizos, 99;
Antoniadis, Dudas, Sagnotti, 99;
Antoniadis, Derendinger, Kounnas, 99;
Derendinger, Kounnas,
Petropoulos, Zwirner, 04;
.....,

See also F. Zwirner, J. Louis, ... talks

4. Some examples of Geometrical Fluxes

- **Breaking of supersymmetry a la Scherk-Schwarz**

In the language of freely acting orbifolds, this corresponds to a **twist** induced by an R-symmetry operator and a **shift** in one internal coordinate.

The gravitino becomes massive due to the modification of the boundary conditions (in $D = 4$ Planck mass units)

$$m_{3/2}^2 = g^2 \frac{Q^2}{R^2}$$

Q is the R-symmetry charge

g_s is the string coupling constant

R is the compactification radius of the shifted coordinate.

What is the induced superpotential in the effective $N = 1$ description?

What is the flux interpretation of this specific model in the heterotic or type IIA orientifolds?

Choose the **R-symmetry operator** which induces the **rotation in the ij plane**

$$Q_{ij} = \oint dz [\Psi_i \Psi_j + x_i \partial x_j - (i \leftrightarrow j)]$$

$\Psi_i \rightarrow$ **2-d world sheet left-handed fermions**
 x_i **the internal compactified coordinates.**

Strictly speaking, the operator Q **is not well defined**, since the internal coordinates are compactified \rightarrow **only discrete rotations are permitted** \leftrightarrow the crystallographic symmetries of the momentum lattice.

Switching on the **deformation** on the world sheet

$$\delta S_{ws} = F_{ij}^{(k)} Q_{ij} \bar{\partial} x_k,$$

corresponds to switch on **a non-zero** $F_{ij}^{(k)}$
→ a magnetic flux of the graviphotons

$$A_M^{(k)} = G_M^k + B_M^k, \quad M = i, j$$

G_M^k and B_M^k are the $D = 10$ metric and antisymmetric tensor fields compactified on a S^1 cycle associated with x^k .

Only discrete rotations make sense → quantization of the magnetic fluxes.

The structure constant coefficients f_{IJ}^K of the $N = 4$ gauged supergravity are given **in terms of the magnetic fluxes** $F_{ij}^{(k)}$.

The induced superpotential in the $N = 1$ language (after the $Z_2 \times Z_2$ projections) reads

$$\begin{aligned} W &= e^{-K/2} F_{2,3}^1 (\sigma_1^1 + \rho_1^1) \sigma_2^2 \sigma_3^2 \\ &= N_{flux} 1 (T_2 + U_2) (T_3 + U_3) \end{aligned}$$

x^k is taken in the 1st complex plane
 x^i and x^j in the second and third planes

Some comments are in order:

- The shifted direction has to be taken left-right symmetric; that is the reason of the $\sigma_1^l + \rho_1^l$ combination
- The choice of $l = 1, 2$ corresponds to the two directions of the 1st complex plane. The two choices are equivalent via $U_1 \leftrightarrow 1/U_1$ duality transformation

- **The twisted directions are taken only left-moving.** The R-symmetry operators in heterotic are left-moving. This is the reason that **only the σ_i^l appear in the superpotential.** Here also the choice of $l = 2$ is equivalent to the $l = 1$ by means of U_i -duality transformations

Having the $N = 1$ superpotential and the Kähler potential

$$K = -\log(S+\bar{S}) - \sum_{A=1}^3 [\log(T_A+\bar{T}_A) + \log(U_A+\bar{U}_A)]$$

we can determine the potential.

The potential is flat in the field directions S, T and U with broken supersymmetry.
(no-scale model)

$$\frac{G_S G_{\bar{S}}}{G_{S\bar{S}}} = \frac{G_{T_1} G_{\bar{T}_1}}{G_{T_1\bar{T}_1}} = \frac{G_{U_1} G_{\bar{U}_1}}{G_{U_1\bar{U}_1}} = 1$$

$$\frac{V}{N^2} = \frac{|T_2 - \bar{U}_2|^2 |T_3 + U_3|^2 + |T_3 - \bar{U}_3|^2 |T_2 + U_2|^2}{2^6 \text{Re}S \text{Re}U_1 \text{Re}T_1 \text{Re}U_2 \text{Re}T_2 \text{Re}U_3 \text{Re}T_3}$$

$$T_A = \bar{U}_A, \quad A = 2, 3 \quad \text{at the minimum}$$

The gravitino mass is *independent of the moduli* $T_A, U_A, A = 2, 3$

$$m_{3/2}^2 = \frac{N^2}{(S + \bar{S})(U_1 + \bar{U}_1)(T_1 + \bar{T}_1)} = g_s^2 \frac{Q^2}{R_1^2}$$

- $SU(2)_k \times SU(2)_{k'}$ - gauging in heterotic

The $N = 1$ superpotential is determined from the **left- and right- moving structure constants** of the left- and right-moving $SU(2)_k \times SU(2)_{k'}$. This generates non trivial σ_A and ρ_A terms in the superpotential

$$W = e^{-K/2} A_l (\sigma_1^l \sigma_2^l \sigma_3^l + \rho_1^l \rho_2^l \rho_3^l)$$

$$\begin{aligned}
W &= iN (T_1 + U_1)(T_2 + U_2)(T_3 + U_3) \\
&\quad + iN (T_1 - U_1)(T_2 - U_2)(T_3 - U_3) \\
&\quad + N' (T_1 U_1 + 1)(T_2 U_2 + 1)(T_3 U_3 + 1) \\
&\quad + N' (T_1 U_1 - 1)(T_2 U_2 - 1)(T_3 U_3 - 1)
\end{aligned}$$

After minimization of the potential:

$$\begin{aligned}
\frac{G_S G_{\bar{S}}}{G_{S\bar{S}}} &= 1 \\
\frac{G_{T_A} G_{\bar{T}_A}}{G_{T_A \bar{T}_A}} &= \frac{G_{U_A} G_{\bar{U}_A}}{G_{U_A \bar{U}_A}} = 0, \quad A = 1, 2, 3 \\
T_A = \bar{T}_A = U_A = \bar{U}_A &= 1 \quad A = 1, 2, 3
\end{aligned}$$

The potential is negative with runaway behavior in the S direction

$$V = -2 m_{3/2}^2 = -2 \frac{N^2 + N'^2}{(S + \bar{S})}$$

This is precisely the form of the **Dilaton potential** in the heterotic theory on $SU(2)_k \times SU(2)_{k'}$.

Indeed, because of the **central charge deficit** $\delta\hat{c}$ coming from the $SU(2)_k \times SU(2)_{k'}$ six-dimensional compactification

$$\delta\hat{c} = -\frac{4}{k+2} - \frac{4}{k'+2}$$

a negative potential is generated which in the **Einstein frame** takes precisely the above form with

$$N^2 = \frac{2}{k+2}, \quad N'^2 = \frac{2}{k'+2}$$

- $SU(2)_k \times SU(2)_{k'}$ perturbative and non-perturbative gauging in heterotic

$$W = -iS W[SU(2)_k] + W[SU(2)_{k'}]$$

$$\begin{aligned} W = & S N (T_1 + U_1)(T_2 + U_2)(T_3 + U_3) \\ & + S N (T_1 - U_1)(T_2 - U_2)(T_3 - U_3) \\ & + N' (T_1 U_1 + 1)(T_2 U_2 + 1)(T_3 U_3 + 1) \\ & + N' (T_1 U_1 - 1)(T_2 U_2 - 1)(T_3 U_3 - 1) \end{aligned}$$

After minimization of the potential:

$$\frac{G_S G_{\bar{S}}}{G_{S\bar{S}}} = \frac{G_{T_A} G_{\bar{T}_A}}{G_{T_A \bar{T}_A}} = \frac{G_{U_A} G_{\bar{U}_A}}{G_{U_A \bar{U}_A}} = 0, \quad A = 1, 2, 3$$

$$S = \frac{N'}{N}, \quad T_A = \bar{T}_A = U_A = \bar{U}_A = 1, \quad A = 1, 2, 3$$

Stabilization of all moduli \rightarrow AdS₄-solution
with unbroken supersymmetry

$$V = -3m_{3/2}^2$$

This is similar to the stabilization of all the moduli found recently in Type IIA, D_6 orientifold, by combining the RR-fluxes and the geometrical fluxes suitably.

The $N = 4$ gauging found in type IIA was based is based on $SU(2)_k \times E_{k'}^3$

Derendinger-Kounnas-
Petropoulos- Zwirner

Conclusion

Illustration and application of a **general method** that relates the $N = 1$ **effective Kähler potential and the superpotential** to a consistent orbifold and/or orientifold projections of **gauged $N = 4$ supergravity**.

Derivation of the effective superpotential $N = 4 \rightarrow N = 1$ for the main moduli in the presence of general fluxes

ω^3, H^3, H^2	In heterotic
ω^3, H^3, H^2	In Type II asymmetric
$\omega^3, H^3, F^6, F^4, F^2, F^0$	in Type IIA
F^1, F^3, H^3, ω^3	in Type IIB

We identify the **correspondence** between various admissible fluxes, $N = 4$ gauging and $N = 1$ superpotential terms.

Construction of explicit examples with different features:

- Stabilization of four moduli, $V \geq 0$:
No-scale models.
- Stabilization of less than four moduli, $V > 0$: **de Sitter like, runaway solutions with possible cosmological interest.**
- Models based on compact “gaugings”, $V < 0$: **Domain-Wall Solutions, Five-brane solutions with non trivial Dilaton or else.**
- Models which admit a supersymmetric AdS_4 vacuum **with all moduli stabilized.**